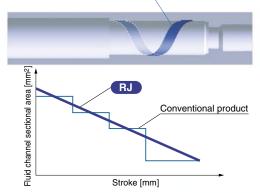
Shock Absorber

Soft type

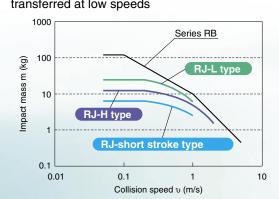
Stops transported • objects softly

Unique mechanism to achieve a variable sectional area of the fluid channel proportional to the stroke

Smooth absorption with a spiral groove structure



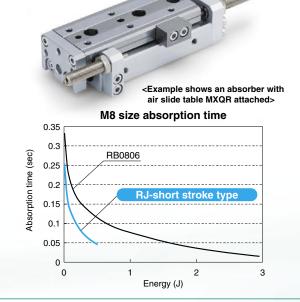
Suitable for softy stopping light objects or objects transferred at low speeds



30% reduced • absorption time

(compared with SMC RB series) Shortened takt time of short stroke actuators, such

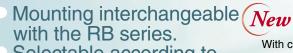
as air slide tables.



Cap type and short stroke

type added!

Offering greater optimization.



Selectable according to impact mass and collision speed.

- Standard stroke L type **0.05** to **1 m/s**
- Standard stroke H type **0.05** to **2 m/s**
- Short stroke type 0.05 to 1 m/s

New Short stroke type

With cap

Series RJ



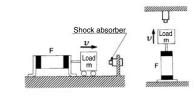
Shock Absorber Series RJ Model Selection 1

Model Selection Graph

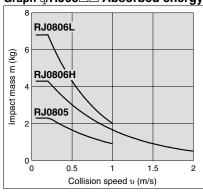
* The model selection graphs 1 to 2 are at room temperature (20 to 25°C).

■ Type of Impact
Free horizontal impact
Impact of air cylinder actuation
(Horizontal/Upward)

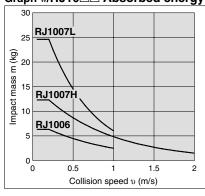
Check the procedure "Model Selection Step" from $\boxed{1}$ to $\boxed{3}$ prior to use.



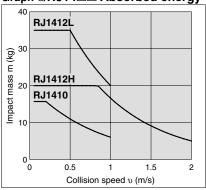
Graph g/RJ08□□ Absorbed energy



Graph w/RJ10□□ Absorbed energy



Graph e/RJ14□□ Absorbed energy

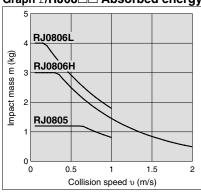


■ Type of Impact Impact of air cylinder actuation (Downward)

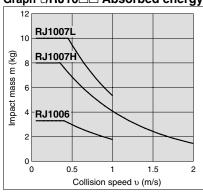
Check the procedure "Model Selection Step" from 1 to 3 prior to use.



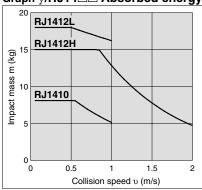
Graph r/RJ08□□ Absorbed energy



Graph t/RJ10□□ Absorbed energy



Graph y/RJ14□□ Absorbed energy



Model Selection Graph

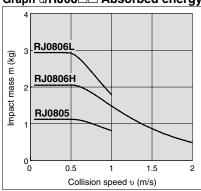
* The model selection graphs 1 to 2 are at room temperature (20 to 25°C).

■ Type of Impact Free fall impact

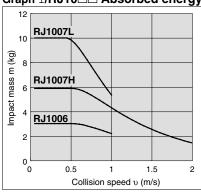
Check the procedure "Model Selection Step" from 1 to 3 prior to use.



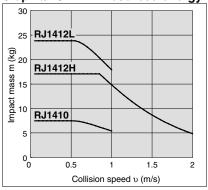
Graph u/RJ08□□ Absorbed energy



Graph i/RJ10□□ Absorbed energy



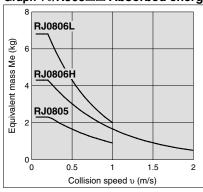
Graph o/RJ14□□ Absorbed energy



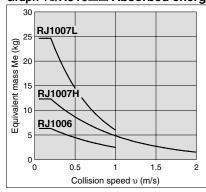
■ Type of Impact

Others (such as thrust impact or swing impact other than air cylinder actuation)

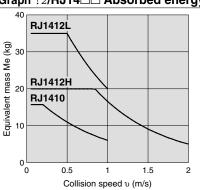
Check the procedure "Model Selection Step" from $\boxed{1}$ to $\boxed{2}$ to calculate the equivalent mass Me prior to use.



Graph ! 0/RJ08□□ Absorbed energy Graph ! 1/RJ10□□ Absorbed energy



Graph 12/RJ14□□ Absorbed energy



Shock Absorber Series RJ Model Selection 2

Model Selection

Model Sel	ection Step	Example of Selection				
Im Im Im Fr Fr	Type of impact ☐ Impact of thrust of load (Horizontal) ☐ Impact of thrust of load (Downward) ☐ Impact of thrust of load (Upward) ☐ Free horizontal impact (Impact of inertial force ☐ Free fall impact ☐ Swing impact (With torque)		1 Type of impact	Impact of thrust of load (Horizontal) (Impact of thrust from sources other than air cylinder actuation) Shock absorber		
2 Operatir	ng conditions		Note 1)	4)		
Symbol	-	Unit	Collision speed 0	υ		
m	Impact mass	kg	Kinetic energy E ₁	$\frac{1}{2} \cdot \mathbf{m} \cdot v^2$		
υ	Collision speed	m/sec	Tamotic chargy =:	2 m °		
h	Dropping height	m	Thrust energy E ₂	F∙S		
ω	Angle speed	rad/sec				
r	Distance between rotational centre and impact point	m	Absorbed energy E	E ₁ + E ₂		
F	Thrust	N	Note 2)			
Т	Torque	N⋅m	Equivalent mass Me	<u>2</u> √2 · E		
n	Operating frequency	cycle/min				
t	Ambient temperature	°C	2	m= 5 kg υ= 0.5 m/s		
Ψ	Friction coefficient		Operating conditions	F= 150 N n = 30 cycle/min t = 25°C		
Ensure : bient te * Be av	ation of specifications and precate the collision speed, thrust, operating frequence mperature and atmosphere fall within the space of the minimum installation radius in impacts.	uency, am- ecifications.	3 Confirmation of specifications and precautions	• Confirmation of specifications υ ··· 0.5 < 1.0 (max.), 2.0 (max.) t ··· -10 (min.) < 25 < 60 (max.) F ··· 150 < 422 (max.) YES		
Calculat	ion of kinetic energy E1 te the kinetic energy E1 by using the fort the impact type.	nula accor-	4 Calculation of kinetic energy E1	● Kinetic energy E1 Use [Formula] to calculate E1 by using 5.0 for m and 0.5 for υ. E1 ≈ 0.63J		
	ion of thrust energy E2 te the thrust energy E2 by selecting arily.	ı a model	5 Calculation of thrust energy E ₂	● Thrust energy E ₂ Select the RJ1007L temporarily and obtain E ₂ by using the formula. $E_2 \approx 1.05J$		
Calculate maximur	ion of equivalent mass Me e the absorbed energy E to confirm it is not m m absorbed energy of the temporarily selected energy when the mass $Me = \frac{2}{v^2} \cdot E$		6 Calculation of equivalent mass Me	• Equivalent mass Me Use Formula "Absorbed energy E = E1 + E2 = 0.63 + 1.05 = 1.68 J" to calculate Me by using E and 0.5 for υ. Me ≈ 13.4 kg		
Substitu speed w the tem tion of a	n of applicable model Ite the obtained equivalent mass Me, and oby using "Model Selection Graph" ① to ① porarily selected model is compatible with application. If satisfactory, then the temporel will be the applicable one. Caution on Selection	to check if the condi-	7 Check adequacy of the selected model RJ1007	• Selection of applicable model According to Graph ①, the temporarily selected RJ1007L satisfies Me = 13.4 kg < 14.5 kg, resulting in an operating frequency of n = 30 < 70, without causing a problem.		
it is necessary conditions. If the	shock absorbers to operate accurately for to select a model that is well-suited to you be impact energy is smaller than 5% of the gy, select a model that is one class smaller.	ur operating e maximum		Select the RJ1007L.		

1	Type	of Im	pact
---	------	-------	------

Type of	Impact of thrust of load (Downward) (Impact of thrust from sources other than air cylinder actuation)	Impact of thrust of load (Upward) (Impact of thrust from sources other than air cylinder actuation)	Load on conveyor (Horizontal)	Free fall impact	Swing impact (With torque)
impact		υ Load m	Load m d	Load m V	
Collision speed	υ	υ	υ	√2 gh	ω· R
Kinetic energy E ₁	$\frac{1}{2} \cdot \mathbf{m} \cdot v^2$	$\frac{1}{2} \cdot \mathbf{m} \cdot v^2$	$\frac{1}{2} \cdot \mathbf{m} \cdot v^2$	m∙g∙h	$\frac{1}{2} \cdot I \cdot \omega^2$
Thrust energy E2	F·S+m·g·S	F·S-m·g·S	m·g·μ·S	m·g·S	T⋅ <u>S</u>
Absorbed energy E	E ₁ + E ₂	E ₁ + E ₂	E ₁ + E ₂	E ₁ + E ₂	E ₁ + E ₂
Equivalent mass Me	$\frac{2}{v^2} \cdot \mathbf{E}$	2/ _{V²} ⋅ E	$\frac{2}{v^2} \cdot \mathbf{E}$	<u>2</u> ⋅ E	<u>2</u> ⋅ E

Note 1) This is the momentary speed at which an object is impacting against a shock absorber. The collision speed is $\upsilon=2\overline{\upsilon}$ when the speed (average speed $\overline{\upsilon}$) is calculated from the air cylinder's stroke time.

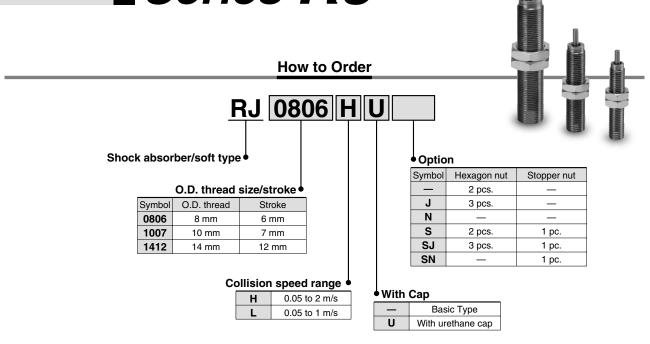
Note 2) This is the theoretical mass, which is converted into the mass of the impacting material under no thrust collision conditions. Hence, $\mathsf{E}=\frac{1}{2}\cdot\mathsf{Me}\cdot\upsilon^2$

<Symbol>

Symbol	Specifications	Unit
Е	Absorbed energy	J
E1	Kinetic energy	J
E2	Thrust energy	J
F	Thrust	N
g	Gravitational acceleration (9.8)	m/s²
h	Dropping height	m
I Note 3)	Moment of inertia around the centre of gravity	kg∙m²
n	Operating frequency	cycle/min
R	Distance between rotational centre and impact point	m
S	Shock absorber's stroke	m
Т	Torque	N⋅m
t	Ambient temperature	°C
υ	Collision speed	m/s
m	Impact mass	kg
Me	Equivalent mass	kg
ω	Angle speed	rad/s
μ	Friction coefficient	_
	· · · · · · · · · · · · · · · · · · ·	

Note 3) For the formula for moment of inertia I (kg·m²), refer to the rotary actuator's catalogue.

Shock Absorber Series RJ



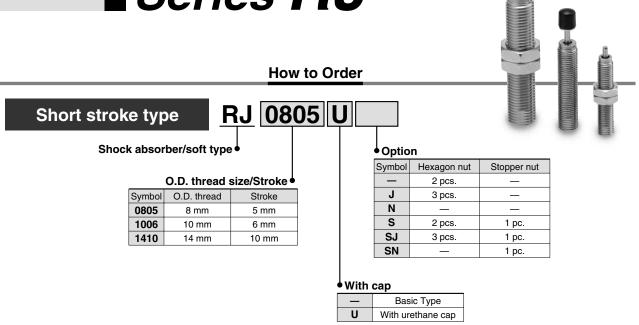
Specifications

	Basic type	•	RJ08	306	RJ1	1007	RJ1	412	
Model	With cap Collision speed range		RJ080	6□U	RJ10	07□U	RJ1412□U		
			н	L	н	L	н	L	
Max. absorbed ei	nergy (J) N	lote)	1		;	3	10	0	
O.D. thread size ((mm)		8		1	0	1-	4	
Stroke (mm)	troke (mm)			6		7		2	
Collision speed (Collision speed (m/s)		0.05 to 2 0.05 to 1		0.05 to 2 0.05 to 1		0.05 to 2	0.05 to 1	
Max. operating free	quency (cy	cle/min) Note)	80	1	7	0	4:	5	
C(AI)		Extended	2.8		5.4		6.4		
Spring force (N)		Retracted	5.4	ļ	8	.4	17.4		
Max. allowable th	nrust (N)		24	5	42	22	814		
Ambient temperature (°C)					-10 to 60 (f	No freezing)			
)4/=:-b+ (-)		Basic type	15	i	2	23	65		
Weight (g)		With cap	16	;	2	25	70		

Note) Max. absorbed energy and max. operating frequency values are at room temperature (20 to 25 $^{\circ}\text{C}$).



Shock Absorber Series RJ

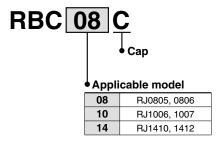


Specifications

Model	Basic type	RJ0805	RJ1006	RJ1410				
With c		RJ0805U	RJ1006U	RJ1410U				
Max. absorbed energy (J)	Note)	0.5	1.5	3.7				
O.D. thread size (mm)		8	10	14				
Stroke (mm)		5	6	10				
Collision speed (m/s)			0.05 to 1					
Max. operating frequency (cy	cle/min) Note)	80	70	45				
Coving force (N)	Extended	2.8	5.4	6.4				
Spring force (N)	Retracted	4.9	8.0	14.6				
Max. allowable thrust (N)		245	422	814				
Ambient temperature (°C)			-10 to 60 (No freezing)					
Woight (a)	Basic type	15	23	65				
Weight (g)	With cap	16	25	70				

Note) Max. absorbed energy and max. operating frequency values are at room temperature (20 to 25°C).

Replacement Part no./Cap (Resin part only)



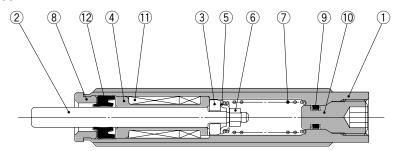
Caps cannot be mounted on basic types. Please specify a type with cap when ordering.



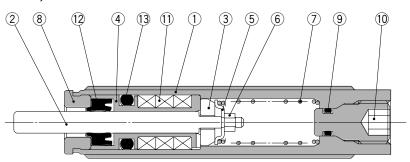
Series **RJ**

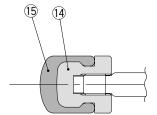
Construction

RJ08



RJ10, 14



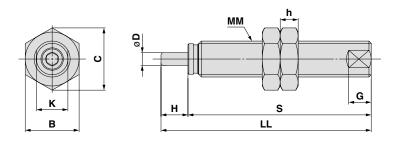


Component Parts

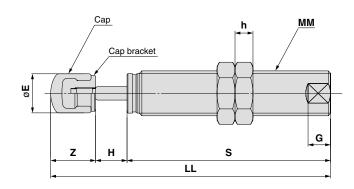
No.	Description	Material	Treatment
1	Tube	Special steel	Electroless nickel plated
2	Piston rod	Special steel	Electroless nickel plated
3	Piston	Stainless steel	
4	Bearing	Special bearing material	
5	Spring guide	Tool steel	Zinc chromated
6	Lock ring	Copper	
7	Return spring	Steel wire	Zinc chromated
8	Stopper	Structural steel	Electroless nickel plated
9	O-ring	Synthetic rubber	
10	Plug		H: Electroless nickel plated
10	riug	_	L: Black electroless nickel plated
11	Accumulator	Synthetic rubber	
12	Rod seal	Synthetic rubber	
13	O-ring	Synthetic rubber	
14	Cap bracket	Structural steel	Zinc chromated
15	Сар	Urethane	

Dimensions

Basic type



With cap



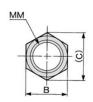
Mo	dal	Dimensions						H	exagon n	nut	With cap			
Model		D	Н	LL	MM	S	G	K	В	С	h	E	LL	Z
RJ0806□	RJ0806□U	2.8	6	46.8	M8 x 1.0	40.8	5	7	12	13.9	4	6.8	55.3	8.5
RJ1007□	RJ1007□U	3	7	52.3	M10 x 1.0	45.3	7	9	14	16.2	4	8.7	62.3	10
RJ1412□	RJ1412□U	5	12	79.1	M14 x 1.5	67.1	8	12	19	21.9	6	12	92.6	13.5
RJ0805	RJ0805U	2.8	5	45.8	M8 x 1.0	40.8	5	7	12	13.9	4	6.8	54.3	8.5
RJ1006	RJ1006U	3	6	51.3	M10 x 1.0	45.3	7	9	14	16.2	4	8.7	61.3	10
RJ1410	RJ1410U	5	10	77.1	M14 x 1.5	67.1	8	12	19	21.9	6	12	89.6	13.5

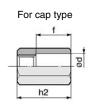
^{*} The dimensions of H- and L-type are the same.

Option

Stopper nut For basic type



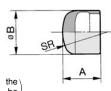




Mo	del	Dimensions						
Basic type	With cap	В	С	h ₁	h2	MM	d	f
RB08S	RBC08S	12	13.9	6.5	23	M8 x 1.0	9	15
RB10S	RBC10S	14	16.2	8	23	M10 x 1.0	11	15
RB14S	RBC14S	19	21.9	11	31	M14 x 1.5	15	20

Replacement Parts

Сар



* Replacement parts for the cap type. Cannot be mounted on the basic type. Material: Polyurethane

Model		Dimensions							
wodei	Α	В	SR						
RBC08C	6.5	6.8	6						
RBC10C	9	8.7	7.5						
RBC14C	12.5	12	10						

Series **RJ**

Foot Bracket for Shock Absorber

Foot mounting bracket is available for the RJ series.

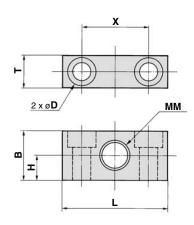


Part No.

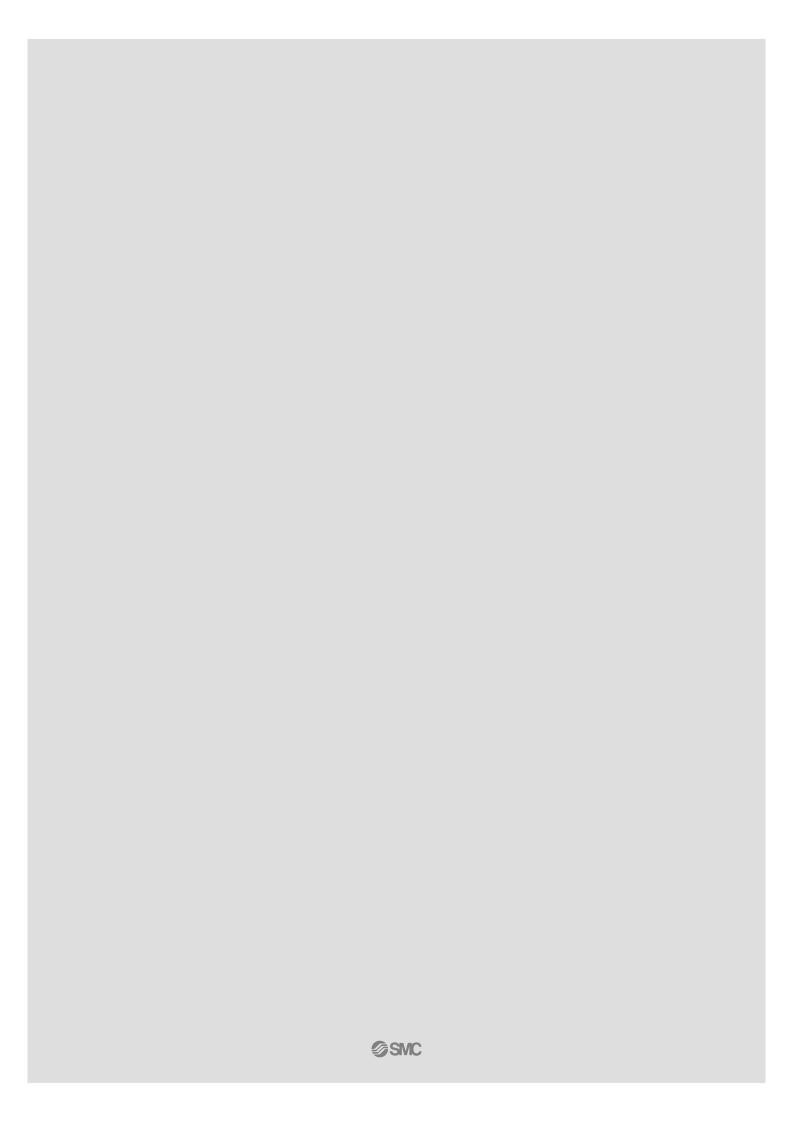
Part no.	Applicable absorber
RB08-X331	RJ0806
RB10-X331	RJ1007
RB14-X331	RJ1412

^{*} Order the foot bracket separately.

Dimensions



Model	В	D	Н	L	ММ	Т	Х	Mounting bolt
RB08-X331	15	4.5 drill, 8 counterbore depth 4.4	7.5	32	M8 x 1.0	10	20	M4
RB10-X331	19	5.5 drill, 9.5 counterbore depth 5.4	9.5	40	M10 x 1.0	12	25	M5
RB14-X331	25	9 drill, 14 counterbore depth 8.6	12.5	54	M14 x 1.5	16	34	M8





Series RJ Specific Product Precautions 1

Be sure to read this before handling. Refer to back cover for Safety Instructions, "Handling Precautions for SMC Products" (M-E03-3) for Common Precautions.

Selection

A Danger

1. Absorbed energy

Select a model so that the aggregated energy of an impacting material should not exceed the maximum absorbed energy. Otherwise, it could cause changes in properties or result in damaging the shock absorber.

2. Equivalent mass

Select a model so that the equivalent mass should not exceed the allowable range. Otherwise, pulsation could occur in buffer capacity and deceleration force, thus making it difficult to absorb shock smoothly.

3. Collision speed

Use the product within the specified collision speed range. Otherwise, it could cause the changes in buffer characteristics or result in damaging the shock absorber.

⚠ Warning

1. Static load

Design the system so that any other forces than the buffer capacity or impacts should not be applied to the piston rod which is stopped at the retracted state.

⚠ Caution

1. Maximum operating frequency

Design the system in the conditions under which it is not used at the frequency exceeding the specified maximum operating frequency.

2. Stroke

The specified maximum absorbed energy cannot be exerted unless the full stroke is used.

3. Work surface of an impacting material

The contact surface of an impacting material with which the piston rod comes into contact must be highly rigid.

A high surface compression load is applied to the contact surface of the impacting material with which the piston rod comes into contact. Therefore, the contact surface must be highly rigid (hardness of HRC35 or more).

4. Be aware of the backlash of the impacting material.

When used in a conveyor line, the object may be pushed back by the built-in spring force after energy is absorbed. For backlash, refer to the spring force in the specifications. (page 5)

5. Selection of size

As the number of operation proceeds, the maximum absorbed energy of shock absorbers will be decreased by the reasons such as abrasion, or deterioration, etc. of the internal working fluid. Taking this into consideration, selecting a size which is 20 to 40% affordable against the amount of absorbed energy is recommended.

Reaction force

In general, the values of reaction force (reactive force generated during operation) generated by the operating speed will vary in oil hydraulic shock absorber. The RJ series can adapt to such this fast/slow speed and can absorb shock smoothly in a wide range of speed.

But, take note the stroke time could be long, and the motion would not be smooth, etc., depending on the operating conditions. If this would be a problem, we recommend the stroke amount should be restricted by using our optional component "stopper nut", etc.

⚠ Caution

7. Parallel usage

When using multiple shock absorbers in parallel, energy will not be divided evenly because of differences in product dimensions and devices. For this reason, select the following options.

E= Ea/N/0.6

E: Energy used per shock absorber

Ea: All energies

N: The number of shock absorbers used in parallel.

Operating Environment

⚠ Danger

1. Operation in an environment which requires explosion-proof

- When mounting in places where static electricity is accumulated, implement a distribution of electrical energy by grounding.
- Do not use materials which might cause to spark by collision for the buffer face.

Marning

1. Pressure

Do not use the product in the vacuum state which is substantially different from the atmospheric pressure (above sea level) and in the atmosphere under being pressurized.

2. Using inside a clean room

Do not use the product in a clean room, as it could contaminate the clean room.

⚠ Caution

1. Temperature range

Do not use the product, exceeding the specified allowable temperature range. Seal could be softened or hardened or worn out, or leading to working fluid leak, deterioration, or buffer characteristic changes.

2. Deterioration by atmosphere

Do not use the product in the presence of salt damage, sulfurous acid gas which makes the metal corroded, or solvent which makes the seal deteriorated.

3. Deterioration by ozone

Do not use the product under the direct sunlight on the beach, or by the mercury lamp, or the ozone generator, because the rubber material will be deteriorated by ozone.

4. Cutting oil, water, blown dust

Do not use the product under the condition where the liquid such as cutting oil, water, solvent, etc. is exposed either directly or in atomized form to the piston rod, or where blown dust could be adhered around the piston rod. This could cause malfunction.

5. Vibration

When vibrations are applied on an impacting material, implement a secure guide on the impacting material.





Series RJ Specific Product Precautions 2

Be sure to read this before handling. Refer to back cover for Safety Instructions, "Handling Precautions for SMC Products" (M-E03-3) for Common Precautions.

Mounting

△ Warning

 Before performing installation, removal, or stroke adjustment, make sure to cut the power supply to the equipment and verify that the equipment has stopped.

2. Installation of protective cover

We recommend the protective cover should be installed for fear that workers might be getting close during the operation.

3. Strength of mounting frame

The mounting frame needs to have sufficient strength. When deciding the strength of the mounting frame, consider the force applied to the mounting frame at the upper limit of operating conditions shown in the below table, and allow a sufficient safety factor.

Model	Load on mounting frame		
RJ0805	380 N		
RJ0806	630 N		
RJ1006	900 N		
RJ1007	1600 N		
RJ1410	1700 N		
RJ1412	2000 N		

Note) Load on mounting frame is at room temperature (20 to 25°C).

⚠ Caution

1. Tightening torque and mounting thread

When threading on the mounting frame in order to mount a shock absorber directly, refer to the below prepared hole dimensions. Observe the below tightening torque of a nut for shock absorber.

If the tightening torque exceeds the below value, the shock absorber could be damaged.

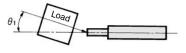
When a shock absorber is mounted on a cylinder, follow the torque values listed on each cylinder.

Model	RJ08□□	RJ10□□	RJ14□□
Thread dimensions (mm)	M8 x 1.0	M10 x 1.0	M14 x 1.5
Thread prepared hole dia. (mm)	ø7.1 ^{+ 0.1}	ø9.1 ^{+ 0.1}	ø12.7 + 0.1
Nut tightening torque (N⋅m)	1.67	3.14	10.8

2. Deviation of impact

Mount the shock absorber so that the point of contact of an impacting material must be within the allowable eccentric angle range. If the eccentric angle exceed 3° , an excessive load could be placed on the bearings, resulting in oil leak in a short time.

Allowable eccentric angle $\theta_1 < 3^{\circ}$



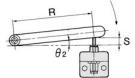
For cap type $\theta_1 < 1^\circ$

⚠ Caution

3. Rotating angle

If swing impacts are involved, the installation must be designed so that the direction in which a load is applied should be perpendicular to the shock absorber's axial centre.

The allowable rotating eccentric angle to the stroke end must be $\theta_2 < 3^\circ$.



Allowable rotating eccentric angle $\theta_2 < 3^\circ$

Installation Requirement for Swing Impacts

(mm)

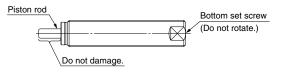
(****)						
Model	S (Stroke)	θ ₂ (Allowable rotating angle)	R (Min. installation radius)			
			Basic type	With cap		
RJ0805	5		96	258		
RJ0806	6	3 °	115	277		
RJ1006	6		115	306		
RJ1007	7		134	325		
RJ1410	10		191	449		
RJ1412	12		229	487		

4. Do not scratch the sliding portion of the piston rod or the outside threads of the outer tube.

Failure to observe this precaution could scratch or gouge the sliding portion of the piston rod, or damage the seals, resulting in oil leak or malfunction. Furthermore, damage to the outside threaded portion of the outer tube could prevent the shock absorber from being mounted onto the frame, or result in malfunction by internal component parts deformation.

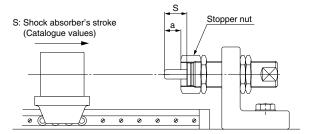
5. Never turn the screw on the bottom of the body.

This is not an adjusting screw. Otherwise, oil leak could occur.



6. Adjust the stopping time by using a stopper nut.

Control the stopping time of the impacting material by turning the stopper nut in or out (thus changing length "a"). After establishing the stopper nut position, use a hexagon nut to secure the stopper nut in place.





Series RJ Specific Product Precautions 3

Be sure to read this before handling. Refer to back cover for Safety Instructions, "Handling Precautions for SMC Products" (M-E03-3) for Common Precautions.

Maintenance

∧ Caution

1. Confirm that the mounting nut is not loosen.

The shock absorber could be damaged if used in a loosen state.

2. Pay attention to any abnormal impact sounds or vibrations.

If impact sounds or vibrations become abnormally high, the shock absorber may reach the end of its service life. Replace the shock absorber. If using continuously in such a state, equipment could be damaged.

Confirm that there is no oil leak on the outer surface.

When a large amount of oil is leaking, replace the product, because it is believed to be happening something wrong with it. If using continuously in such a state, equipment could be damaged.

4. Check for cracks and wear in caps.

For shock absorbers with caps, the caps will wear out first. Replace caps early to prevent damage to colliding objects.

Storage

1. Position of the piston rod during storage

If the product is stored for an extended period (30 days or more) with the piston rod pushed, the absorption capacity could decrease. Avoid this kind of storage condition.

Life and Replacement Period of Product

⚠ Caution

 As a guide, the maximum operating life of the product (number of cycles) when operated within the specifications is as follows.

3 million cycles RJ08□□, 10□□, 14□□

Note) This value (adequate replacement period) is at room temperature (20 to 25°C). The life can depend on conditions such as temperature so the product may need to be replaced before the above number of cycles is reached.

⚠ Safety Instructions

These safety instructions are intended to prevent hazardous situations and/or equipment damage. These instructions indicate the level of potential hazard with the labels of "Caution," "Warning" or "Danger." They are all important notes for safety and must be followed in addition to International Standards (ISO/IEC)*1), and other safety regulations.

Caution indicates a hazard with a low level of risk Caution: which, if not avoided, could result in minor or

moderate injury.

Warning indicates a hazard with a medium level of Warning: risk which, if not avoided, could result in death or

serious injury

⚠ Danger :

Danger indicates a hazard with a high level of risk which, if not avoided, will result in death or serious injury.

*1) ISO 4414: Pneumatic fluid power - General rules relating to systems. ISO 4413: Hydraulic fluid power – General rules relating to systems.

IEC 60204-1: Safety of machinery – Electrical equipment of machines. (Part 1: General requirements) ISO 10218-1: Manipulating industrial robots - Safety.

⚠Warning

- 1. The compatibility of the product is the responsibility of the person who designs the equipment or decides its specifications. Since the product specified here is used under various operating conditions, its compatibility with specific equipment must be decided by the person who designs the equipment or decides its specifications based on necessary analysis and test results. The expected performance and safety assurance of the equipment will be the responsibility of the person who has determined its compatibility with the product. This person should also continuously review all specifications of the product referring to its latest catalogue information, with a view to giving due consideration to any possibility of equipment failure when configuring the
- 2. Only personnel with appropriate training should operate machinery and equipment.

The product specified here may become unsafe if handled incorrectly. The assembly, operation and maintenance of machines or equipment including our products must be performed by an operator who is appropriately trained and experienced.

- 3. Do not service or attempt to remove product and machinery/equipment until safety is confirmed.
 - 1. The inspection and maintenance of machinery/equipment should only be performed after measures to prevent falling or runaway of the driven objects have been confirmed.
 - 2. When the product is to be removed, confirm that the safety measures as mentioned above are implemented and the power from any appropriate source is cut, and read and understand the specific product precautions of all relevant
 - 3. Before machinery/equipment is restarted, take measures to prevent unexpected operation and malfunction.
- 4. Contact SMC beforehand and take special consideration of safety measures if the product is to be used in any of the following
 - 1. Conditions and environments outside of the given specifications, or use outdoors or in a place exposed to direct sunlight.
 - 2. Installation on equipment in conjunction with atomic energy, railways, air navigation, space, shipping, vehicles, military, medical treatment, combustion and recreation, or equipment in contact with food and beverages, emergency stop circuits, clutch and brake circuits in press applications, safety equipment or other applications unsuitable for the standard specifications described in the product catalogue.
 - 3. An application which could have negative effects on people, property, or animals requiring special safety analysis.
 - 4. Use in an interlock circuit, which requires the provision of double interlock for possible failure by using a mechanical protective function, and periodical checks to confirm proper operation.

. Caution

1. The product is provided for use in manufacturing industries.

The product herein described is basically provided for peaceful use in manufacturing industries.

If considering using the product in other industries, consult SMC beforehand and exchange specifications or a contract if necessary

If anything is unclear, contact your nearest sales branch.

Limited warranty and Disclaimer/ Compliance Requirements

The product used is subject to the following "Limited warranty and Disclaimer" and "Compliance Requirements".

Read and accept them before using the product.

Limited warranty and Disclaimer

- 1. The warranty period of the product is 1 year in service or 1.5 years after the product is delivered.*2)
 - Also, the product may have specified durability, running distance or replacement parts. Please consult your nearest sales branch.
- 2. For any failure or damage reported within the warranty period which is clearly our responsibility, a replacement product or necessary parts will be provided. This limited warranty applies only to our product independently, and not to any other damage incurred due to the failure of the product.
- 3. Prior to using SMC products, please read and understand the warranty terms and disclaimers noted in the specified catalogue for the particular products.
 - *2) Vacuum pads are excluded from this 1 year warranty.
 - A vacuum pad is a consumable part, so it is warranted for a year after it is delivered.

 Also, even within the warranty period, the wear of a product due to the use of the vacuum pad or failure due to the deterioration of rubber material are not covered by the limited warranty

Compliance Requirements

- 1. The use of SMC products with production equipment for the manufacture of weapons of mass destruction (WMD) or any other weapon is strictly prohibited.
- 2. The exports of SMC products or technology from one country to another are governed by the relevant security laws and regulations of the countries involved in the transaction. Prior to the shipment of a SMC product to another country, assure that all local rules governing that export are known and followed.

⚠ Safety Instructions

Be sure to read "Handling Precautions for SMC Products" (M-E03-3) before using

SMC Corporation (Europe)

Austria ***** +43 2262622800 office@smc.at **2** +370 5 2308118 www.smc.at Lithuania www.smclt.lt info@smclt.lt Belgium **☎**+32 (0)33551464 www.smcpneumatics.be info@smcpneumatics.be Netherlands **2** +31 (0)205318888 www.smcpneumatics.nl info@smcpneumatics.nl Bulgaria **2**+359 29744492 www.smc.bg office@smc.bg ***** +47 67129020 post@smc-norae.no Norway www.smc-norge.no ★+385 13776674 office@smc.hr Croatia www.smc.hr Poland ★ +48 222119600 www.smc.pl office@smc.pl **2**+420 541424611 Czech Republic office@smc.cz postpt@smc.smces.es www.smc.cz **Portugal 2** +351 226166570 www.smc.eu **☎**+45 70252900 Denmark www.smcdk.com smc@smcdk.com Romania **2** +40 213205111 www.smcromania.ro smcromania@smcromania.ro Estonia **2**+372 6510370 www.smcpneumatics.ee smc@smcpneumatics.ee Russia **2**+7 8127185445 info@smc-pneumatik.ru www.smc-pneumatik.ru **Finland 2**+358 207513513 www.smc.fi smcfi@smc.fi Slovakia **2** +421 413213212 www.smc.sk office@smc.sk France **2**+33 (0)164761000 www.smc-france.fr contact@smc-france.fr Slovenia ***** +386 73885412 office@smc.si www.smc.si **2**+49 (0)61034020 www.smc-pneumatik.de Germany info@smc-pneumatik.de Spain **2** +34 945184100 www.smc.eu post@smc.smces.es **☎**+30 210 2717265 www.smchellas.gr sales@smchellas.gr Sweden **2** +46 (0)86031200 post@smcpneumatics.se Greece www.smc.nu Hungary **☎**+36 23511390 www.smc.hu office@smc.hu Switzerland ***** +41 (0)523963131 www.smc.ch info@smc.ch **2**+353 (0)14039000 smc@entek.com.tr Ireland www.smcpneumatics.ie sales@smcpneumatics.ie Turkey **2**+90 (0)2124440762 www.entek.com.tr Italy **2**+39 (0)292711 www.smcitalia.it mailbox@smcitalia.it UK **2** +44 (0)845 121 5122 www.smcpneumatics.co.uk sales@smcpneumatics.co.uk **2**+371 67817700 Latvia www.smclv.lv info@smclv.lv